5 gZ6C aX: -1.1500 aY: 7.390 gY: -1.7500 gZ: 1.8125

Angles X: -47.8802 Y: 5.3209 Z: -2.3637

G force: 9.7545

1

dTS (ms): 10221

ACC aX: -1.1500 aY: 7.390 gY: -1.7500 gZ: 1.8125

Angles X: -47.8802 Y: 5.3209 Z: -2.3637

G force: 9.7545

1

dTS (ms): 10221

ACC aX: -1.1500 aY: 7.390Orientation Sensor Test

1

dTS (ms): 130111

ACC aX: 0.0000 aY: 0.0000 aZ: 0.0000

Gyro gX: 0.0000 gY: 0.0000 gZ: 0.0000

Angles X: nan Y: nan Z: nan

G force: 0.0000

1

dTS (ms): 10123

ACC aX: 0.0000 aY: 0.0000 aZ: 0.0000

Gyro gX: 0.0000 gY: 0.0000 gZ: 0.0000

Angles X: nan Y: nan Z: nan

G force: 0.0000

1

dTS (ms): 10121

ACC aX: 0.2100 aY: 7.2000 aZ: 5.6900

Gyro gX: 13.0625 gY: -7.3750 gZ: 0.8125

Angles X: -51.6815 Y: -1.3109 Z: 0.6349

G force: 5.0486

1

dTS (ms): 21112

ACC aX: 0.6900 aY: 6.7500 aZ: 7.4600

Gyro gX: -1.8750 gY: 0.1875 gZ: 0.0000

Angles X: -44.9127 Y: -3.1734 Z: 1.3119

G force: 7.7942

1

dTS (ms): 10213

ACC aX: 0.2900 aY: 6.9500 aZ: 6.8600

Gyro gX: -2.0625 gY: -4.4375 gZ: 1.7500

Angles X: -45.1916 Y: -2.2825 Z: 0.9500

G force: 8.8799

1

dTS (ms): 10220

ACC aX: 0.6300 aY: 7.0000 aZ: 6.5900

Gyro gX: 4.5000 gY: 7.0625 gZ: -0.5625

Angles X: -46.0670 Y: -3.1190 Z: 1.3263

G force: 9.2934

1

dTS (ms): 10213

ACC aX: 0.6100 aY: 6.6100 aZ: 7.1800

Gyro gX: 7.8125 gY: 3.9375 gZ: 0.6875

Angles X: -44.1355 Y: -3.3779 Z: 1.3697

G force: 9.5559

1

dTS (ms): 10212

ACC aX: 0.4500 aY: 6.4400 aZ: 7.2000

Gyro gX: 3.0000 gY: 7.7500 gZ: 7.1875

Angles X: -42.8497 Y: -2.9855 Z: 1.1717

G force: 9.6167

1

dTS (ms): 10211

ACC aX: 0.6600 aY: 6.4600 aZ: 7.6500

Gyro gX: -7.9375 gY: -8.7500 gZ: 2.5000

Angles X: -41.3534 Y: -3.4268 Z: 1.2936

G force: 9.8436

1

dTS (ms): 10220

ACC aX: 0.2400 aY: 6.8500 aZ: 7.5700

Gyro gX: 0.6875 gY: 1.3125 gZ: 1.5625

Angles X: -41.7943 Y: -2.2639 Z: 0.8645

G force: 10.0444

1

dTS (ms): 10213

ACC aX: 0.4100 aY: 6.5500 aZ: 6.9500

Gyro gX: 7.5000 gY: -0.5000 gZ: -1.8125

Angles X: -42.6054 Y: -2.3686 Z: 0.9237

G force: 9.7765

1

dTS (ms): 10220

ACC aX: 1.0700 aY: 6.3600 aZ: 8.0100

Gyro gX: 7.6875 gY: 12.8125 gZ: -3.1875

Angles X: -40.2726 Y: -4.3986 Z: 1.6135

G force: 10.0441

1

dTS (ms): 10221

ACC aX: 0.9400 aY: 6.2500 aZ: 7.9700

Gyro gX: 24.8750 gY: 4.6250 gZ: -7.9375

Angles X: -39.0733 Y: -4.8993 Z: 1.7394

G force: 10.1123

1

dTS (ms): 10220

ACC aX: 0.4400 aY: 5.2800 aZ: 8.5300

Gyro gX: 14.6250 gY: -4.1875 gZ: -3.8750

Angles X: -35.0568 Y: -3.5973 Z: 1.1365

G force: 10.0510

1

dTS (ms): 10222

ACC aX: 1.1800 aY: 4.8200 aZ: 8.4600

Gyro gX: 22.0625 gY: 12.8125 gZ: -6.1875

Angles X: -32.1347 Y: -5.4051 Z: 1.5578

G force: 9.9024

1

dTS (ms): 10221

ACC aX: 1.2700 aY: 3.5900 aZ: 9.1600

Gyro gX: 12.3125 gY: 2.2500 gZ: -1.0000

Angles X: -26.2352 Y: -6.5067 Z: 1.5178

G force: 9.8682

1

dTS (ms): 10220

ACC aX: 1.3800 aY: 2.8600 aZ: 9.3500

Gyro gX: 12.3750 gY: 0.0000 gZ: -3.5000

Angles X: -21.1655 Y: -7.3701 Z: 1.3788

G force: 9.8397

1

dTS (ms): 10213

ACC aX: 1.7200 aY: 1.9500 aZ: 9.5500

Gyro gX: 18.9375 gY: 7.9375 gZ: -4.9375

Angles X: -15.8734 Y: -8.8550 Z: 1.2369

G force: 9.8353

1

dTS (ms): 10220

ACC aX: 1.6900 aY: 1.4200 aZ: 9.3300

Gyro gX: 19.1875 gY: 6.2500 gZ: -4.8750

Angles X: -11.9547 Y: -9.5790 Z: 1.0053

G force: 9.6799

1

dTS (ms): 10220

ACC aX: 1.7200 aY: 0.4700 aZ: 9.4300

Gyro gX: 23.1250 gY: -1.4375 gZ: -5.8125

Angles X: -6.9725 Y: -10.0180 Z: 0.6119

G force: 9.6049

1

dTS (ms): 10221

ACC aX: 1.7700 aY: -0.5600 aZ: 9.5600

Gyro gX: 13.2500 gY: 3.6250 gZ: -1.9375

Angles X: -1.2607 Y: -10.3096 Z: 0.1137

G force: 9.6408

1

dTS (ms): 10221

ACC aX: 1.8100 aY: -1.4800 aZ: 9.4800

Gyro gX: 19.3750 gY: -2.0625 gZ: -2.3125

Angles X: 4.3432 Y: -10.5560 Z: -0.4014

G force: 9.6723

1

dTS (ms): 10222

ACC aX: 1.7300 aY: -2.4800 aZ: 9.2700

Gyro gX: 17.6250 gY: 0.1875 gZ: -2.8125

Angles X: 10.2178 Y: -10.4137 Z: -0.9336

G force: 9.6754

1

dTS (ms): 10222

ACC aX: 1.7300 aY: -2.8500 aZ: 8.8800

Gyro gX: 4.8125 gY: 1.0000 gZ: 2.3750

Angles X: 14.3473 Y: -10.4878 Z: -1.3237

G force: 9.5507

1

dTS (ms): 10220

ACC aX: 1.6100 aY: -3.1900 aZ: 8.7600

Gyro gX: 18.5625 gY: 3.4375 gZ: -4.2500

Angles X: 17.4514 Y: -10.1221 Z: -1.5575

G force: 9.4899

1

dTS (ms): 10222

ACC aX: 2.0200 aY: -4.5300 aZ: 8.6800

Gyro gX: 11.8750 gY: 2.9375 gZ: -4.4375

Angles X: 23.1296 Y: -11.0274 Z: -2.2632

G force: 9.7320

1

dTS (ms): 10222

ACC aX: 2.0800 aY: -4.9500 aZ: 8.1000

Gyro gX: 17.4375 gY: 5.3750 gZ: -1.0000

Angles X: 27.6824 Y: -11.7891 Z: -2.9143

G force: 9.6994

1

dTS (ms): 10221

ACC aX: 2.0100 aY: -5.7400 aZ: 7.4700

Gyro gX: 24.8125 gY: 2.1250 gZ: 0.7500

Angles X: 33.0855 Y: -11.9715 Z: -3.5677

G force: 9.6288

1

dTS (ms): 10221

ACC aX: 2.0200 aY: -6.3200 aZ: 7.0500

Gyro gX: 5.7500 gY: -1.7500 gZ: 3.6250

Angles X: 37.9317 Y: -12.0451 Z: -4.1529

G force: 9.6307

1

dTS (ms): 10221

ACC aX: 2.2500 aY: -6.5400 aZ: 6.8600

Gyro gX: 9.4375 gY: 0.0625 gZ: -4.2500

Angles X: 41.0759 Y: -12.7841 Z: -4.8066

G force: 9.6797

1

dTS (ms): 10221

ACC aX: 2.0200 aY: -7.2200 aZ: 6.1100

Gyro gX: 12.3750 gY: -2.5000 gZ: -5.1250

Angles X: 45.8573 Y: -12.4177 Z: -5.2697

G force: 9.6488

1

dTS (ms): 10223

ACC aX: 1.7700 aY: -7.2500 aZ: 6.0200

Gyro gX: 4.2500 gY: -2.1875 gZ: 3.6875

Angles X: 48.2985 Y: -11.4498 Z: -5.1472

G force: 9.6075

1

dTS (ms): 10221

ACC aX: 2.0800 aY: -7.5900 aZ: 5.9800

Gyro gX: 11.4375 gY: 0.3125 gZ: -3.1875

Angles X: 50.2279 Y: -11.8440 Z: -5.5671

G force: 9.7552

1

dTS (ms): 10222

ACC aX: 1.8800 aY: -8.1300 aZ: 4.9700

Gyro gX: 1.0625 gY: 0.5000 gZ: -1.1875

Angles X: 54.8083 Y: -11.4983 Z: -5.9759

G force: 9.7071

1

dTS (ms): 10221

ACC aX: 1.8200 aY: -8.0300 aZ: 5.1200

Gyro gX: 1.5625 gY: -1.1875 gZ: 0.1250

Angles X: 56.2774 Y: -11.1279 Z: -5.9648

G force: 9.6982

1

dTS (ms): 10221

ACC aX: 1.9100 aY: -8.4200 aZ: 5.0500

Gyro gX: 9.4375 gY: 4.7500 gZ: -5.3750

Angles X: 57.8217 Y: -11.0645 Z: -6.1239

G force: 9.8627

1

dTS (ms): 10221

ACC aX: 1.7800 aY: -8.2800 aZ: 4.7500

Gyro gX: 0.7500 gY: 0.8125 gZ: 1.2500

Angles X: 59.0988 Y: -10.7926 Z: -6.1307

G force: 9.7768

1

dTS (ms): 10213

ACC aX: 1.9200 aY: -8.3900 aZ: 4.7000

Gyro gX: 0.8750 gY: 1.5000 gZ: 0.2500

Angles X: 60.0036 Y: -11.0680 Z: -6.4039

G force: 9.7921

1

dTS (ms): 10213

ACC aX: 1.8800 aY: -8.3300 aZ: 4.6100

Gyro gX: 1.3750 gY: 0.1875 gZ: -0.3750

Angles X: 60.5706 Y: -11.1245 Z: -6.5103

G force: 9.7435

1

dTS (ms): 10221

ACC aX: 1.8400 aY: -8.4300 aZ: 4.6100

Gyro gX: 0.2500 gY: -0.0625 gZ: 0.9375

Angles X: 60.9879 Y: -10.9686 Z: -6.4723

G force: 9.7649

1

dTS (ms): 10221

ACC aX: 1.7800 aY: -8.4000 aZ: 4.7500

Gyro gX: 2.5625 gY: 1.1875 gZ: -0.4375

Angles X: 60.7259 Y: -10.6834 Z: -6.2706

G force: 9.7910

1

dTS (ms): 10221

ACC aX: 1.7700 aY: -8.3400 aZ: 4.6500

Gyro gX: 0.5625 gY: -0.6875 gZ: -0.3750

Angles X: 60.7983 Y: -10.5837 Z: -6.2208

G force: 9.7472

1

dTS (ms): 10222

ACC aX: 1.7400 aY: -8.2000 aZ: 4.6800

Gyro gX: -12.3750 gY: -4.6875 gZ: 0.6250

Angles X: 60.5180 Y: -10.5064 Z: -6.1407

G force: 9.6664

1

dTS (ms): 10223

ACC aX: 1.7900 aY: -7.9000 aZ: 5.4100

Gyro gX: -14.6250 gY: -2.3125 gZ: 3.4375

Angles X: 57.8019 Y: -10.5615 Z: -5.8420

G force: 9.6987

1

dTS (ms): 10223

ACC aX: 1.9400 aY: -7.3400 aZ: 5.9200

Gyro gX: -20.2500 gY: -3.6875 gZ: 6.0000

Angles X: 54.1406 Y: -11.1630 Z: -5.7184

G force: 9.6434

1

dTS (ms): 10223

ACC aX: 2.0300 aY: -7.0000 aZ: 6.5200

Gyro gX: -10.1875 gY: 1.4375 gZ: 3.5625

Angles X: 50.2117 Y: -11.6372 Z: -5.4674

G force: 9.7001

1

dTS (ms): 10222

ACC aX: 2.1500 aY: -6.4200 aZ: 7.0100

Gyro gX: -16.4375 gY: -0.6875 gZ: 0.2500

Angles X: 45.9602 Y: -12.2745 Z: -5.2215

G force: 9.7038

1

dTS (ms): 21121

ACC aX: 2.3500 aY: -5.3100 aZ: 7.9600

Gyro gX: -20.3125 gY: -2.0000 gZ: 3.8750

Angles X: 39.1908 Y: -13.1904 Z: -4.7139

G force: 9.7326

1

dTS (ms): 10223

ACC aX: 2.2300 aY: -4.7600 aZ: 8.4300

Gyro gX: -10.1250 gY: 0.1875 gZ: 5.8125

Angles X: 33.7812 Y: -13.1141 Z: -3.9979

G force: 9.8103

1

dTS (ms): 10222

ACC aX: 2.0600 aY: -3.6400 aZ: 8.8300

Gyro gX: -10.8750 gY: -4.8125 gZ: -5.5000

Angles X: 27.5224 Y: -12.6564 Z: -3.1115

G force: 9.7426

1

dTS (ms): 10230

ACC aX: 2.0200 aY: -3.0800 aZ: 8.9900

Gyro gX: -23.4375 gY: -7.0000 gZ: 7.1250

Angles X: 22.7863 Y: -12.3295 Z: -2.4938

G force: 9.7015

1

dTS (ms): 10223

ACC aX: 1.4500 aY: -2.5800 aZ: 9.4200

Gyro gX: -7.0000 gY: -1.0625 gZ: 2.8750

Angles X: 18.6220 Y: -10.1966 Z: -1.6761

G force: 9.7709

1

dTS (ms): 10222

ACC aX: 1.6100 aY: -1.8200 aZ: 9.6000

Gyro gX: -21.0625 gY: -4.2500 gZ: -1.7500

Angles X: 14.2524 Y: -9.7543 Z: -1.2224

G force: 9.8208

1

dTS (ms): 10223

ACC aX: 1.9100 aY: -1.0600 aZ: 9.7400

Gyro gX: -15.9375 gY: 2.9375 gZ: 3.5625

Angles X: 9.8047 Y: -10.4868 Z: -0.9020

G force: 9.8855

1

dTS (ms): 10221

ACC aX: 1.7200 aY: 0.1200 aZ: 9.7300

Gyro gX: -9.4375 gY: -6.6250 gZ: 1.5000

Angles X: 4.0193 Y: -10.2742 Z: -0.3615

G force: 9.8434

1

dTS (ms): 10213

ACC aX: 1.8500 aY: 0.5800 aZ: 9.6900

Gyro gX: -25.5625 gY: 2.6875 gZ: 10.0625

Angles X: -0.0800 Y: -10.5799 Z: 0.0074

G force: 9.8447

1

dTS (ms): 10221

ACC aX: 1.1800 aY: 1.3700 aZ: 9.4100

Gyro gX: -6.5625 gY: -8.7500 gZ: 0.6875

Angles X: -4.5569 Y: -8.6967 Z: 0.3467

G force: 9.6717

1

dTS (ms): 10213

ACC aX: 1.1600 aY: 1.7500 aZ: 9.5900

Gyro gX: -2.1875 gY: -2.2500 gZ: -0.6875

Angles X: -7.7666 Y: -7.6482 Z: 0.5199

G force: 9.7383

1

dTS (ms): 10220

ACC aX: 1.5800 aY: 1.4400 aZ: 9.5900

Gyro gX: -6.1250 gY: 3.5625 gZ: 2.5625

Angles X: -8.1926 Y: -8.5350 Z: 0.6124

G force: 9.7850

1

dTS (ms): 10212

ACC aX: 1.5300 aY: 2.5700 aZ: 9.2000

Gyro gX: -17.3750 gY: 8.8750 gZ: 3.1250

Angles X: -12.2476 Y: -8.8622 Z: 0.9527

G force: 9.7041

1

dTS (ms): 10220

ACC aX: 1.7000 aY: 3.1500 aZ: 9.2300

Gyro gX: 0.8125 gY: -7.6250 gZ: 5.0000

Angles X: -15.9035 Y: -9.4466 Z: 1.3225

G force: 9.7957

1

dTS (ms): 10213

ACC aX: 1.5000 aY: 3.0100 aZ: 9.5400

Gyro gX: -0.9375 gY: 4.3750 gZ: 1.1875

Angles X: -16.8015 Y: -8.9348 Z: 1.3221

G force: 9.9703

1

dTS (ms): 10213

ACC aX: 1.4900 aY: 3.2000 aZ: 9.0000

Gyro gX: -11.5000 gY: 1.4375 gZ: -0.3125

Angles X: -18.3049 Y: -8.9001 Z: 1.4367

G force: 9.8010

1

dTS (ms): 10221

ACC aX: 1.2700 aY: 3.9500 aZ: 8.8400

Gyro gX: -10.8750 gY: -0.5000 gZ: 3.4375

Angles X: -21.4795 Y: -8.1263 Z: 1.5438

G force: 9.7686

1

dTS (ms): 10220

ACC aX: 1.1900 aY: 4.7900 aZ: 7.9400

Gyro gX: -12.9375 gY: -8.7500 gZ: -2.3125

Angles X: -26.6723 Y: -7.7144 Z: 1.8314

G force: 9.5048

1

dTS (ms): 10222

ACC aX: 1.3900 aY: 4.9700 aZ: 8.6800

Gyro gX: -7.3750 gY: -7.9375 gZ: 2.7500

Angles X: -28.4359 Y: -7.8287 Z: 1.9865

G force: 9.8277

1

dTS (ms): 10220

ACC aX: 0.6300 aY: 4.8800 aZ: 8.0800

Gyro gX: -10.6250 gY: -3.1250 gZ: -0.5000

Angles X: -29.8972 Y: -5.6624 Z: 1.5129

G force: 9.6172

1

dTS (ms): 10222

ACC aX: 0.7400 aY: 5.7300 aZ: 8.0800

Gyro gX: -7.2500 gY: -5.9375 gZ: 3.4375

Angles X: -32.9388 Y: -4.8922 Z: 1.4471

G force: 9.7794

1

dTS (ms): 10213

ACC aX: 0.5900 aY: 5.4500 aZ: 8.0200

Gyro gX: -1.9375 gY: 1.3750 gZ: 2.1875

Angles X: -33.6299 Y: -4.1191 Z: 1.2453

G force: 9.7424

1

dTS (ms): 10213

ACC aX: 0.4900 aY: 5.6100 aZ: 8.0600

Gyro gX: 2.6875 gY: -0.4375 gZ: 0.0000

Angles X: -34.2981 Y: -3.4220 Z: 1.0562

G force: 9.7908

1

dTS (ms): 10213

ACC aX: 0.5300 aY: 5.7000 aZ: 8.0100

Gyro gX: -3.5000 gY: -0.0625 gZ: 0.3750

Angles X: -34.9256 Y: -3.2368 Z: 1.0185

G force: 9.8203

1

dTS (ms): 10220

ACC aX: 0.5200 aY: 5.7900 aZ: 7.8500

Gyro gX: -1.4375 gY: 0.1875 gZ: 0.2500

Angles X: -35.7411 Y: -3.1354 Z: 1.0112

G force: 9.7908

1

dTS (ms): 10212

ACC aX: 0.4900 aY: 5.8300 aZ: 7.9500

Gyro gX: 0.1250 gY: 3.3750 gZ: -0.5625

Angles X: -36.0242 Y: -2.9754 Z: 0.9676

G force: 9.8346

1

dTS (ms): 10213

ACC aX: 0.4900 aY: 5.8600 aZ: 7.8600

Gyro gX: -1.0625 gY: -2.1875 gZ: 0.3750

Angles X: -36.3990 Y: -2.9127 Z: 0.9578

G force: 9.8244

1

dTS (ms): 10220

ACC aX: 0.4800 aY: 5.9500 aZ: 7.8300

Gyro gX: -1.8750 gY: 0.6875 gZ: -1.8125

Angles X: -36.8572 Y: -2.8476 Z: 0.9490

G force: 9.8359

1

dTS (ms): 10220

ACC aX: 0.4400 aY: 5.9400 aZ: 7.7400

Gyro gX: -4.7500 gY: 1.3125 gZ: -0.1875

Angles X: -37.2119 Y: -2.7021 Z: 0.9098

G force: 9.7976

1

dTS (ms): 10220

ACC aX: 0.4500 aY: 6.0900 aZ: 7.8300

Gyro gX: -3.4375 gY: -3.4375 gZ: 2.0000

Angles X: -37.5788 Y: -2.6442 Z: 0.8998

G force: 9.8701

1

dTS (ms): 10220

ACC aX: 0.3500 aY: 6.3300 aZ: 7.2600

Gyro gX: -3.5000 gY: 6.6250 gZ: 4.8125

Angles X: -39.4871 Y: -2.3389 Z: 0.8395

G force: 9.7380

1

dTS (ms): 10213

ACC aX: 0.0500 aY: 6.2000 aZ: 7.7200

Gyro gX: -15.8750 gY: -1.1875 gZ: 2.2500

Angles X: -39.0886 Y: -1.2032 Z: 0.4271

G force: 9.8262

1

dTS (ms): 10221

ACC aX: 0.2400 aY: 7.1800 aZ: 6.7200

Gyro gX: -19.4375 gY: 5.9375 gZ: -2.3125

Angles X: -43.3850 Y: -1.3134 Z: 0.5225

G force: 9.8096

1

dTS (ms): 10221

ACC aX: -0.1800 aY: 7.3900 aZ: 6.4600

Gyro gX: -8.3125 gY: -9.6875 gZ: 5.1875

Angles X: -46.3874 Y: -0.0128 Z: 0.0055

G force: 9.8007

1

dTS (ms): 10220

ACC aX: -0.1600 aY: 7.8100 aZ: 6.1500

Gyro gX: -14.6250 gY: -0.0625 gZ: 0.8750

Angles X: -49.3732 Y: 0.5053 Z: -0.2323

G force: 9.8673

1

dTS (ms): 10222

ACC aX: -0.3000 aY: 8.0800 aZ: 5.2400

Gyro gX: -18.3750 gY: -0.8125 gZ: 2.3125

Angles X: -53.5422 Y: 1.2039 Z: -0.6074

G force: 9.7174

1

dTS (ms): 10222

ACC aX: -0.4200 aY: 8.6500 aZ: 4.9100

Gyro gX: -16.7500 gY: -1.6250 gZ: 3.6250

Angles X: -57.3651 Y: 1.8822 Z: -1.0298

G force: 9.8302

1

dTS (ms): 10222

ACC aX: -0.7300 aY: 8.8000 aZ: 3.7100

Gyro gX: -24.0625 gY: 0.2500 gZ: 1.6250

Angles X: -62.6737 Y: 3.2468 Z: -1.9773

G force: 9.6543

1

dTS (ms): 10220

ACC aX: -0.4000 aY: 9.4100 aZ: 3.0600

Gyro gX: -16.4375 gY: 3.0625 gZ: -1.7500

Angles X: -67.8571 Y: 2.7373 Z: -1.8416

G force: 9.7590

1

dTS (ms): 10222

ACC aX: -0.7900 aY: 9.3800 aZ: 2.7800

Gyro gX: -6.1875 gY: -3.1875 gZ: 6.3750

Angles X: -70.9613 Y: 3.7781 Z: -2.6934

G force: 9.7769

1

dTS (ms): 10221

ACC aX: -0.7800 aY: 9.6300 aZ: 1.9800

Gyro gX: -17.4375 gY: 3.5625 gZ: -1.9375

Angles X: -75.0571 Y: 4.2054 Z: -3.2308

G force: 9.8034

1

dTS (ms): 10222

ACC aX: -1.0700 aY: 9.8200 aZ: 0.7800

Gyro gX: -10.3125 gY: -3.3750 gZ: 4.9375

Angles X: -80.7988 Y: 5.3288 Z: -4.5360

G force: 9.8201

1

dTS (ms): 10222

ACC aX: -1.1000 aY: 9.7000 aZ: 0.5000

Gyro gX: -15.1875 gY: 1.1875 gZ: -0.6250

Angles X: -84.2265 Y: 5.9591 Z: -5.3879

G force: 9.7805

1

dTS (ms): 10222

ACC aX: -1.0000 aY: 9.4300 aZ: -1.2500

Gyro gX: -20.6875 gY: 3.6875 gZ: -1.7500

Angles X: -91.4837 Y: 6.0221 Z: -6.1798

G force: 9.5979

1

dTS (ms): 10223

ACC aX: -1.1700 aY: 9.4200 aZ: -1.0100

Gyro gX: -15.0625 gY: -1.6875 gZ: 6.5625

Angles X: -94.0251 Y: 6.5859 Z: -7.0645

G force: 9.5613

1

dTS (ms): 10223

ACC aX: -1.0900 aY: 9.6600 aZ: -1.5000

Gyro gX: -5.6250 gY: -4.6875 gZ: 0.6250

Angles X: -96.7001 Y: 6.4669 Z: -7.2690

G force: 9.7043

1

dTS (ms): 10221

ACC aX: -1.0100 aY: 9.3800 aZ: -2.3100

Gyro gX: -11.8125 gY: -4.7500 gZ: 1.8125

Angles X: -100.6279 Y: 6.2046 Z: -7.4739

G force: 9.6905

1

dTS (ms): 10230

ACC aX: -1.5300 aY: 9.0500 aZ: -3.2300

Gyro gX: -17.5000 gY: -1.3750 gZ: 2.7500

Angles X: -105.5808 Y: 7.7943 Z: -10.2535

G force: 9.6802

1

dTS (ms): 10231

ACC aX: -1.2000 aY: 8.9100 aZ: -2.9000

Gyro gX: -11.6875 gY: -2.0000 gZ: 1.1250

Angles X: -106.9131 Y: 7.5260 Z: -10.1428

G force: 9.5495

1

dTS (ms): 10231

ACC aX: -1.2800 aY: 9.0300 aZ: -3.5000

Gyro gX: -7.3750 gY: -7.1875 gZ: 3.1875

Angles X: -109.2874 Y: 7.5328 Z: -10.6018

G force: 9.6636

1

dTS (ms): 10231

ACC aX: -1.5400 aY: 8.4600 aZ: -3.8500

Gyro gX: -12.1250 gY: -5.5000 gZ: 2.7500

Angles X: -112.0988 Y: 8.5607 Z: -12.6870

G force: 9.5197

1

dTS (ms): 10231

ACC aX: -1.1200 aY: 8.6900 aZ: -3.9400

Gyro gX: 0.1875 gY: -3.0625 gZ: 1.6250

Angles X: -113.3662 Y: 7.5317 Z: -11.4370

G force: 9.5646

1

dTS (ms): 10223

ACC aX: -1.4400 aY: 8.7100 aZ: -3.7900

Gyro gX: 2.3750 gY: -3.2500 gZ: 2.8125

Angles X: -113.4484 Y: 8.1316 Z: -12.3633

G force: 9.5877

1

dTS (ms): 10223

ACC aX: -1.3900 aY: 8.7000 aZ: -4.0100

Gyro gX: 5.0625 gY: 1.1250 gZ: -1.5000

Angles X: -114.1650 Y: 8.2008 Z: -12.6382

G force: 9.6379

1

dTS (ms): 10223

ACC aX: -1.3800 aY: 8.4700 aZ: -4.3300

Gyro gX: 1.6875 gY: -0.6875 gZ: 1.1875

Angles X: -115.7645 Y: 8.2328 Z: -13.0807

G force: 9.6207

1

dTS (ms): 10223

ACC aX: -1.3100 aY: 8.5100 aZ: -3.9700

Gyro gX: 3.6875 gY: -0.4375 gZ: 1.0000

Angles X: -115.3519 Y: 8.0739 Z: -12.7284

G force: 9.5439

1

dTS (ms): 10223

ACC aX: -1.5400 aY: 8.7600 aZ: -3.9300

Gyro gX: -2.1875 gY: 0.8125 gZ: 1.1250

Angles X: -114.6930 Y: 8.6504 Z: -13.4618

G force: 9.6420

1

dTS (ms): 10223

ACC aX: -1.4800 aY: 8.3800 aZ: -4.2200

Gyro gX: -3.0000 gY: -2.4375 gZ: 4.9375

Angles X: -115.8048 Y: 8.8230 Z: -14.0238

G force: 9.5616

1

dTS (ms): 10230

ACC aX: -1.5000 aY: 8.5400 aZ: -4.3000

Gyro gX: -2.5625 gY: -0.6875 gZ: 1.1875

Angles X: -116.3141 Y: 8.8746 Z: -14.2442

G force: 9.6256

1

dTS (ms): 10230

ACC aX: -1.5500 aY: 8.5200 aZ: -4.2400

Gyro gX: 0.8125 gY: -0.4375 gZ: 0.3125

Angles X: -116.3929 Y: 9.0816 Z: -14.5964

G force: 9.6346

1

dTS (ms): 10223

ACC aX: -1.6400 aY: 8.4500 aZ: -4.2600

Gyro gX: -0.6875 gY: -1.9375 gZ: 2.8125

Angles X: -116.5914 Y: 9.4938 Z: -15.3126

G force: 9.6176

1

dTS (ms): 10230

ACC aX: -1.5800 aY: 8.4600 aZ: -4.3900

Gyro gX: -1.3750 gY: -0.1250 gZ: 0.5625

Angles X: -117.0510 Y: 9.4492 Z: -15.3772

G force: 9.6414

1

dTS (ms): 10230

ACC aX: -1.6000 aY: 8.4400 aZ: -4.3200

Gyro gX: 4.0625 gY: 0.1875 gZ: -1.0000

Angles X: -117.0810 Y: 9.5202 Z: -15.5010

G force: 9.6271

1

dTS (ms): 10222

ACC aX: -1.5600 aY: 8.6500 aZ: -3.8800

Gyro gX: 11.2500 gY: -0.8750 gZ: 0.0000

Angles X: -115.4749 Y: 9.4266 Z: -14.8825

G force: 9.6135

1

dTS (ms): 10230

ACC aX: -1.1800 aY: 8.8700 aZ: -3.4100

Gyro gX: 12.6250 gY: -1.0000 gZ: -0.6250

Angles X: -113.0272 Y: 8.1433 Z: -12.2830

G force: 9.5838

1

dTS (ms): 10231

ACC aX: -1.5900 aY: 9.0200 aZ: -2.9600

Gyro gX: 12.2500 gY: 1.2500 gZ: -4.0625

Angles X: -110.3536 Y: 8.9032 Z: -12.7716

G force: 9.5977

1

dTS (ms): 10230

ACC aX: -1.3100 aY: 9.2700 aZ: -1.9600

Gyro gX: 10.5625 gY: -0.1875 gZ: -0.5625

Angles X: -105.7261 Y: 8.3588 Z: -11.0230

G force: 9.5544

1

dTS (ms): 10231

ACC aX: -1.1400 aY: 9.5100 aZ: -1.5900

Gyro gX: 11.6250 gY: 3.1250 gZ: -5.6250

Angles X: -102.2663 Y: 7.4744 Z: -9.2671

G force: 9.6247

1

dTS (ms): 10223

ACC aX: -1.1800 aY: 9.6700 aZ: -1.1100

Gyro gX: 9.8125 gY: -1.0000 gZ: 0.9375

Angles X: -99.0931 Y: 7.1714 Z: -8.4063

G force: 9.7118

1

dTS (ms): 10221

ACC aX: -0.9700 aY: 9.6200 aZ: -0.4500

Gyro gX: 13.6250 gY: 3.0000 gZ: -1.1875

Angles X: -95.5655 Y: 6.4015 Z: -7.0540

G force: 9.6783

1

dTS (ms): 10222

ACC aX: -1.0500 aY: 9.5300 aZ: 0.5300

Gyro gX: 15.3125 gY: 1.5625 gZ: -1.8125

Angles X: -90.7695 Y: 6.3519 Z: -6.4376

G force: 9.6090

1

dTS (ms): 10221

ACC aX: -0.9100 aY: 9.8100 aZ: 0.8000

Gyro gX: 22.1875 gY: 0.3125 gZ: -5.0625

Angles X: -87.7414 Y: 5.7625 Z: -5.5400

G force: 9.7494

1

dTS (ms): 10221

ACC aX: -0.5700 aY: 9.6400 aZ: 1.7600

Gyro gX: 8.3125 gY: 0.3125 gZ: -2.1875

Angles X: -83.2719 Y: 4.4308 Z: -3.9392

G force: 9.7599

1

dTS (ms): 10220

ACC aX: -0.6100 aY: 9.5100 aZ: 2.1300

Gyro gX: 8.0625 gY: 5.0000 gZ: -3.5625

Angles X: -80.0264 Y: 3.9688 Z: -3.3322

G force: 9.7495

1

dTS (ms): 10220

ACC aX: -0.4600 aY: 9.4200 aZ: 2.6500

Gyro gX: 20.5000 gY: -1.4375 gZ: 0.3125

Angles X: -76.8613 Y: 3.2687 Z: -2.5939

G force: 9.7626

1

dTS (ms): 10220

ACC aX: -0.3800 aY: 9.3700 aZ: 3.6000

Gyro gX: 13.3125 gY: -1.9375 gZ: -1.0000

Angles X: -72.4702 Y: 2.6618 Z: -1.9508

G force: 9.8944

1

dTS (ms): 10222

ACC aX: -0.0600 aY: 9.2800 aZ: 3.7700

Gyro gX: 7.5000 gY: -0.5000 gZ: -1.5625

Angles X: -69.9362 Y: 1.3806 Z: -0.9656

G force: 9.9518

1

dTS (ms): 10221

ACC aX: 0.0400 aY: 8.7900 aZ: 4.1400

Gyro gX: 15.5625 gY: 0.3750 gZ: -3.6875

Angles X: -67.1304 Y: 0.5016 Z: -0.3328

G force: 9.8114

1

dTS (ms): 10213

ACC aX: 0.0200 aY: 8.6500 aZ: 5.0300

Gyro gX: 8.0000 gY: -1.3125 gZ: 0.8750

Angles X: -63.0746 Y: 0.1601 Z: -0.0982

G force: 9.8985

1

dTS (ms): 10213

ACC aX: -0.0800 aY: 7.8600 aZ: 5.7400

Gyro gX: 12.3125 gY: 1.7500 gZ: -1.5000

Angles X: -58.0442 Y: 0.3308 Z: -0.1835

G force: 9.7761

1

dTS (ms): 10221

ACC aX: 0.0900 aY: 7.8100 aZ: 6.0500

Gyro gX: 12.6250 gY: 2.0625 gZ: -2.3125

Angles X: -54.8348 Y: -0.1406 Z: 0.0729

G force: 9.8203

1

dTS (ms): 10220

ACC aX: 0.1900 aY: 7.3400 aZ: 6.5000

Gyro gX: 14.4375 gY: -2.6875 gZ: 1.3125

Angles X: -51.3382 Y: -0.6746 Z: 0.3242

G force: 9.7972

1

dTS (ms): 10220

ACC aX: 0.0400 aY: 6.9600 aZ: 6.8000

Gyro gX: 4.9375 gY: -0.2500 gZ: -0.6875

Angles X: -48.2279 Y: -0.4344 Z: 0.1944

G force: 9.7486

1

dTS (ms): 10220

ACC aX: 0.3300 aY: 6.8000 aZ: 7.2800

Gyro gX: 12.3125 gY: -0.3125 gZ: 0.1875

Angles X: -45.3507 Y: -1.2483 Z: 0.5216

G force: 9.8582

1

dTS (ms): 10213

ACC aX: -0.0300 aY: 6.4000 aZ: 7.2000

Gyro gX: 10.0000 gY: -5.8750 gZ: -1.4375

Angles X: -43.3273 Y: -0.4720 Z: 0.1875

G force: 9.7287

1

dTS (ms): 10222

ACC aX: 0.6600 aY: 6.4400 aZ: 7.7900

Gyro gX: -3.0625 gY: -2.0625 gZ: -0.9375

Angles X: -41.2311 Y: -2.3010 Z: 0.8657

G force: 9.9396

1

dTS (ms): 10221

ACC aX: 0.1900 aY: 6.6100 aZ: 7.6300

Gyro gX: -2.7500 gY: 6.3125 gZ: -9.5625

Angles X: -41.0493 Y: -1.6237 Z: 0.6079

G force: 10.0254

1

dTS (ms): 10221

ACC aX: 1.2400 aY: 6.9800 aZ: 7.2500

Gyro gX: -19.1875 gY: -20.2500 gZ: 0.7500

Angles X: -42.6274 Y: -4.6108 Z: 1.7998

G force: 10.0743

1

dTS (ms): 10223

ACC aX: 0.7800 aY: 6.5700 aZ: 7.0600

Gyro gX: -2.1875 gY: -16.6250 gZ: 11.9375

Angles X: -42.7968 Y: -4.6179 Z: 1.8104

G force: 9.8550

1

dTS (ms): 10222

ACC aX: 0.3500 aY: 7.2000 aZ: 6.5200

Gyro gX: -69.7500 gY: 7.6250 gZ: -11.3125

Angles X: -45.5553 Y: -3.2249 Z: 1.3544

G force: 9.7688

1

dTS (ms): 10222

ACC aX: 1.9500 aY: 8.8700 aZ: 4.8500

Gyro gX: 21.6250 gY: 33.7500 gZ: -18.3125

Angles X: -54.3773 Y: -7.6267 Z: 3.9220

G force: 9.9443

1

dTS (ms): 10222

ACC aX: 1.2500 aY: 7.1300 aZ: 7.3600

Gyro gX: 23.5625 gY: -36.1875 gZ: 8.1875

Angles X: -48.6192 Y: -7.2795 Z: 3.2918

G force: 10.1129

1

dTS (ms): 10222

ACC aX: 0.9800 aY: 6.2500 aZ: 7.3500

Gyro gX: 33.8125 gY: 1.6875 gZ: -12.1875

Angles X: -44.1644 Y: -6.4977 Z: 2.6384

G force: 9.8586

1

dTS (ms): 10221

ACC aX: 1.3800 aY: 8.1300 aZ: 9.6700

Gyro gX: -10.0000 gY: 3.2500 gZ: 0.8750

Angles X: -41.6500 Y: -6.3401 Z: 2.4137

G force: 11.4192

1

dTS (ms): 10221

ACC aX: -0.5400 aY: 5.7900 aZ: 7.2600

Gyro gX: -4.7500 gY: 1.5000 gZ: 4.5000

Angles X: -40.1115 Y: -1.5173 Z: 0.5540

G force: 10.2145

1

dTS (ms): 10220

ACC aX: 0.7900 aY: 4.9100 aZ: 10.8400

Gyro gX: 7.5625 gY: 26.5625 gZ: 24.0625

Angles X: -30.8534 Y: -2.8847 Z: 0.7962

G force: 11.0523

1

dTS (ms): 10222

ACC aX: 0.1700 aY: 6.2500 aZ: 8.0000

Gyro gX: 4.8750 gY: -16.4375 gZ: -12.5625

Angles X: -34.6350 Y: -1.8699 Z: 0.5831

G force: 10.5360

1

dTS (ms): 10223

ACC aX: 0.3100 aY: 6.4200 aZ: 7.0300

Gyro gX: -2.3750 gY: -15.3125 gZ: -8.0625

Angles X: -38.7132 Y: -1.8716 Z: 0.6576

G force: 9.9573

1

dTS (ms): 10222

ACC aX: 0.1600 aY: 6.6700 aZ: 7.3000

Gyro gX: -0.3125 gY: -5.0625 gZ: -0.7500

Angles X: -40.7449 Y: -1.3544 Z: 0.5030

G force: 9.9146

1

dTS (ms): 10221

ACC aX: 0.1200 aY: 6.5600 aZ: 7.1400

Gyro gX: 1.8125 gY: 1.5625 gZ: -0.5000

Angles X: -41.7419 Y: -1.0031 Z: 0.3825

G force: 9.7934

1

dTS (ms): 10213

ACC aX: 0.2500 aY: 6.5600 aZ: 7.4900

Gyro gX: 3.6250 gY: -0.2500 gZ: 1.2500

Angles X: -41.4488 Y: -1.2443 Z: 0.4708

G force: 9.8847

1

dTS (ms): 10213

ACC aX: 0.0200 aY: 6.5600 aZ: 7.1800

Gyro